## 2 JC17 Rec'd PCT/PTO 20 JUN 2005

## In the Claims

## **CLAIMS**

## What is claimed is:

1. (Currently Amended) A pneumatic Pneumatic servomotor for an assisted braking, comprising a casing 5 (2) having a longitudinal axis (X) and in which a lowpressure chamber (10) and a variable-pressure chamber (8) are defined, in an airtight manner, by a moving partition wall (12) bearing a pneumatic piston (18) in 10 its middle part, a three-way valve (20), arranged at the rear part of the pneumatic piston (18)controlled by an actuating rod (27), the three-way valve comprising first a valve (22)for a equalization between the low-pressure chamber (10) and 15 the variable-pressure chamber (8), and a second valve (24) for the high-pressure supply of the variablepressure chamber (8), said supply valve (24) comprising a valve seat, borne by a first longitudinal end of a distributor plunger (28) and receiving a longitudinal 20 end of the actuating rod (27), said distributor plunger (28) having, at a second longitudinal in the opposite direction relative to the first longitudinal end, a finger (30), which is perpendicular to the longitudinal axis (X) and which comes into contact with a face of a 25 reaction disk (32) a braking operation, onreaction disk (32) being accommodated in a housing (34) integral with a push rod (36) for the actuation of a cylinder, said master housing (34) comprising pneumatic braking-assistance device (D) fitted with a 30 cage (38), a first closed longitudinal end of which is integral with the push rod (36) while its second open longitudinal end is closable by an annular ring (44) integral with the cage (38) and by a reaction piston (42) fitted for a sliding travel inside the ring (44) along the longitudinal axis (X), said reaction piston 35

(42) being reactionnally kept against the ring (44) by a resilient means (40) having a prestress (ch) and bearing by its rear end on the closed first end of the cage (38), and wherein the an area consisting of the rear faces (50, 52) of the annular ring (44) and of the reaction piston (42), respectively, constitutes the a front longitudinal end of the housing (34) of reaction disk, characterised in that said device comprises plastically-deformable means (68, 74) for the adjustment of the braking characteristics.

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- 2. (Currently Amended) <u>The pneumatic servomotor</u> Servomotor according to claim 1, characterised in that the resilient means (40) is a helical spring.
- 3. (Currently Amended) The pneumatic servomotor Servomotor according to claim 1 or claim 2, characterised in that the first means (68) are capable of setting a predetermined value (Vj) to a clearance (j) between the planes containing the rear faces (52, 50) of the reaction piston (42) and of the annular ring (44), respectively.
  - 4. (Currently Amended) The pneumatic servomotor Servomotor according to the preceding claim 3, characterised in that the first means (68) are disposed between a front face (66) of the annular ring (44) and a rear face (62) of a flange (60) extending radially outwards from the periphery of the body of the reaction piston (42).
  - 5. (Currently Amended) The pneumatic servomotor Servomotor according to the preceding claim 4, characterised in that said first means (68) consist of a collar.
  - 6.(Currently Amended) <u>The pneumatic servomotor</u> Servomotor according to claim 4, characterised in that said first means (68) consist of a ring-shaped protrusion, made in one piece with the annular ring

- (44) and extending axially forwards from the front face (66) of the annular ring.
- 7. (Currently Amended) The pneumatic servomotor Servomotor according to claim 4, characterised in that said first means (68) consist of a ring-shaped protrusion, made in one piece with the flange (60) and extending axially rearwards from the rear face (62) of the flange (60).

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- 8.(Currently Amended) The pneumatic servomotor

  10 Servomotor according to claim 7 any one of the preceding claims, characterised in that the second means (74) are capable of setting a predetermined value (Vch) to the stressing (ch) of the resilient means (40).
- 15 9.(Currently Amended) The pneumatic servomotor Servomotor according to the preceding claim <u>8</u>, characterised in that the second means (74)accommodated inside the emergency-braking assistance device (D) so as to modify the axial position of the 20 closed first end of the cage (38) relative to the reaction piston (42).
  - 10. (Currently Amended) The pneumatic servomotor Servomotor according to the preceding claim 9, characterised in that the second means (74) consist of a collar, disposed between the front face (66) of the annular ring (44) and the rear face of an inner bearing surface (47) of the cage (38).
  - 11.(Currently Amended) The pneumatic servomotor Servomotor according to claim 9, characterised in that the second means (74) consist of a ring-shaped protrusion, made in one piece with the annular ring (44) and extending axially from the front face (66) of the annular ring towards an inner bearing surface (47) of the cage (38).
- 35 12. (Currently Amended) The pneumatic servomotor

Servomotor according to claim 9, characterised in that the cage (38) comprises a sleeve (381), which is closed at its first front longitudinal end (383) by a cap (382) integral with the push rod (36), and in that the second means (74) are disposed between the front longitudinal end of the sleeve (381) and a rear face of the cap (382).

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- 13. (Currently Amended) The pneumatic servomotor Servomotor according to the preceding claim 12, characterised in that the second means (74) consist of a ring-shaped protrusion, made in one piece with the sleeve (381) and extending axially towards the cap (382).
- 14. (Currently Amended) The pneumatic servomotor 15 to <del>claim 12 or</del> Servomotor according claim characterised in that said cap (382) is interlocked with the sleeve (381) by means of a ring-shaped extension, which is arranged radially outside relative to the ring-shaped protrusion constituting the second 20 means (74), and capable of folding over onto the front face of the cap (382) owing to a plastic deformation.
  - 15.(Currently Amended) A manufacturing Manufacturing process for a pneumatic servomotor for an assisted braking, fitted with an emergency-braking assistance device according to any one of the preceding claims, characterised in that it comprises, among other features including the following step:
- a preliminary step, in which the first means (68) are plastically deformed in an axial direction so as to set a predetermined value (Vj) to the clearance (j) between the rear faces (52, 50) of the a reaction piston (42) and of the an annular ring (44), respectively;
- a subsequent step, in which the <u>a</u> second means (74) are plastically deformed in an axial

direction so as to set a predetermined value (Vch) to the stressing (ch) of  $\frac{1}{2}$  resilient means (40).

16. (Currently Amendeded) The manufacturing process wherein a device Device for the implementation of the preliminary step of the process according to the claim 15, characterised preceding in in that comprises a first element (202) and a second element (204), movable relative to the first element along the longitudinal axis (X), said first element having a reference surface, which defines the predetermined value (Vj) of the clearance (j), while second element (204)comprises a ring-shaped pressing surface, which cooperates with the front face (64) of the flange (60) of the reaction piston (42).

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17. (Currently Amended) The manufacturing process Device for the implementation of the subsequent step of the process according to in claim 15 16, characterised in that it comprises a third element (302) and a fourth element (304), movable relative to the third element along the longitudinal axis (X), said third element having a ring-shaped supporting surface for the front face (66) of the annular ring, and a means (307) for the detection of the force applied to the reaction piston (42) by the resilient means (40), while the fourth element (304) comprises a surface for a force application to the cage (38), so as to deform the second means (74) plastically in the course of an axial travel of the fourth element (304) towards the third element (302), in such a way that the stressing of the resilient means (40) is equal to the predetermined value (Vch).